

VASAVI COLLEGE OF ENGINEERING (Autonomous)
 IBRAHIMBAGH, HYDERABAD – 500 031
Department of Mechanical Engineering
INTRODUCTION TO INDUSTRIAL ROBOTICS
 (Stream: Robotics)
 (Open Elective-I)
 SYLLABUS FOR B.E.III-SEMESTER

L:T:P(Hrs/week):2:0:0	SEE Marks:60	Course Code: U22OE310ME
Credits :02	CIE Marks:40	Duration of SEE: 03Hours

COURSE OBJECTIVE	COURSE OUTCOMES
The objective of the course is to study industrial robot components, configuration, sensors, drives, applications and programming through experiential learning.	On completion of the course, students will be able to
	1 explain configuration of industrial robots and summarize various applications.
	2 interpret various elements of the industrial robots
	3 Develop methodology to represent position and orientation of industrial robot links in spatial coordinate system.
	4 classify various sensors used in industrial robots and interface between the human user and an industrial robot using various programming languages.

CO-PO and CO-PSO mapping																
CO	PO mapping												PSO mapping			
	1	2	3	4	5	6	7	8	9	10	11	12	1	2	3	
CO1	3	2			1	2	2					2	3	1	2	
CO2	3	2			1	2	2					2	3	1	2	
CO3	3	2			1	2	2					2	3	1	2	
CO4	3	2			1	2	2					2	3	1	2	

UNIT-I
ROBOT BASICS

Robot-Basic concepts, Need, Law, History, Anatomy, specifications.
 Robot configurations-cartesian, cylindrical, polar, articulated and SCARA. Parallel robots

ROBOT APPLICATIONS

Application in industry – material handling, loading & unloading, processing, welding & painting, assembly and inspection

UNIT-II
ROBOT ELEMENTS

End effectors-Classification, Types of Mechanical actuation, Gripper design, Robot joints types, Robot drive system types: Electrical, pneumatic and hydraulic. Position and velocity feedback devices

UNIT-III
ROBOT COORDINATE SYSTEMS

Coordinate frames, Rotation matrix, Euler angles, Roll pitch and yaw angle representation, Composite rotations, Homogeneous Transformation matrix.

UNIT-IV
ROBOT SENSORS

Sensors in robots – Touch sensors-Tactile sensors – Proximity and range sensors. Force sensors

Robot programming


On line programming, teach pendant control, Lead through, Walk through, off line programming, Task programming.

Learning Resources:

1. Mikell P. Groover, Mitchell Weiss, Roger N Nagel and Nicholas G Odrey, "Industrial Robotics Technology, Programming and Applications", Tata Mc Graw-Hill Publishing Company Limited , 2008.
2. Deb.S.R and Sankha Deb, "Robotics Technology and Flexible Automation", Tata Mc Graw Hill Publishing Company Limited, 2010.
3. Klafter R.D, Chmielewski T.A, and Negin. M, "Robotic Engineering: An Integrated Approach", Prentice Hall of India Pvt. Ltd.,1994.
4. K.S. Fu, R.C. Gonzalez and C.S.G. Lee , "Robotics control, sensing, vision and intelligence", Tata Mc Graw-Hill Publishing Company Limited, 2008
5. R.K. Mittal and I. J. Nagrath "Robotics and Control", Tata Mc Graw-Hill Publishing Company Limited,2003.

The break-up of CIE: Internal Tests+Assignments + Quizzes

1	No. of Internal Tests:	02	Max.Marks for each Internal Test:	30
2	No. of Assignments:	02	Max. Marks for each Assignment:	05
3	No. of Quizzes:	02	Max. Marks for each Quiz Test:	05
	Duration of Internal Test:	90 Minutes		


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